## Today's Agenda

## Image Formation

## Image Formation at a Glance

## Exposure



## The Response of Cones to Color

Three kinds of cones: S, L, and M

- $S$ cones respond to blue
- M cones respond to green
- L cones respond to red

Response levels to illumination are

$$
\begin{aligned}
s & =\int S(\lambda) P(\lambda) d \lambda \\
m & =\int M(\lambda) P(\lambda) d \lambda \\
l & =\int L(\lambda) P(\lambda) d \lambda
\end{aligned}
$$

- where $s, m, l$ are scalars
- this implies that we humans perceive light as a 3-D space

And this 3D space is very complex

- for instance, it's not Euclidean


## Humans Perceive a 3D Color Space

## We can't distinguish all distributions

- metamers: two colors with different spectral distributions but identical $s, m, l$ values
- these would look identical



## The Simplest Camera: Pinhole Camera

Mount a piece of film in a lightproof box with a single pinhole in it
Pinhole focuses light on the film

- Lens degenerates to a point - no distortion
- One-to-one correspondence between 3D object point and 2D image point
- only select light ray can go through the hole (the hole is reduced to a point)
- note that image on film is flipped upside down



## Picture Taken by Pinhole Camera

How to make pinhole camera?

- http://www. exploratorium.edu/light walk/camera todo.html



## Synthetic Camera Model



## The Equation of Projection



Only one coordinate system - camera coordinate system

## The Equation of Perspective Projection

## Cartesian coordinates:

- We have, by similar triangles, that

$$
(x, y, z) \rightarrow\left(x^{\prime}, y^{\prime}, z^{\prime}\right)=\left(-f \frac{x}{z},-f \frac{y}{z},-f\right)
$$

- Ignore the third coordinate, and assume the image plane is before the camera, we get

$$
(x, y, z) \rightarrow(u, v)=\left(\frac{f}{z} x, \frac{f}{z} y\right) \text { Isotropic } \begin{aligned}
& \text { scaling }
\end{aligned}
$$

3D object point $\rightarrow$ 2D image point
The perspective projection is non-linear!

## Properties of Perspective Projection

## Points project to points

## Lines project to lines

Planes project to the whole or half image

- A plane may only has half of its area in the projection side

Scaling and foreshortening
Angles are not preserved

- Parallel lines may be not projected to parallel lines unless they are parallel to the image plane

Degenerate cases

- Line through focal point projects to a point.
- Plane through focal point projects to line


## The Structure of a Typical Camera

Film is light sensitive material
Lens focuses light on film
Aperture is the opening of lens

- opening may vary in size
- controls the total energy of incoming lights

Shutter restricts access to film

- can open for variable periods
- controls total energy that hits the film

Film is replaced by Charged Couple Device (CCD) in a digital camera

## Refractive Lenses

Refraction happens when light rays travel between materials

- results from dependence of the speed of light on the material

Real cameras use refractive lenses

- typically made of glass or plastic
- bend incoming light rays
- parallel incoming rays converge on the focal point



## Refractive Lenses



## Basic Optics: Thin Lens



Field of View: $\omega=2 \arctan \frac{d}{f}$
Depth of view (DOF) is inversely proportional to the focus length (f) and inversely proportional to the aperture (d)

## Raster Image Representation

Continuous representation needs to be sampled and quantized to generate a discrete representation

Each image is represented by a rectangular grid of pixels $P[x, y]$ each pixel $p$ will store a color value

- RGB triple for color images
- single value for grayscale (or monochrome) images



## Basic Color Representation in Graphics

For each pixel, we will treat colors as a 3-D space of (r, $\boldsymbol{g}, \boldsymbol{b}$ ) triples

- all colors will be composed from three primary colors: red, green, blue
- the value of each $(r, g, b)$ is between 0 and 1
- coefficients represent relative contribution of each primary


0 Colors along Red axis

## Raster Image Representation

Can separate RGB color image into 3 distinct color channels

- each by itself is a monochrome image



## Question

What are those colors?
$\left(\begin{array}{ll}\mathrm{g} & \mathrm{b}\end{array}\right)=\left(\begin{array}{lll}0 & 0 & 0\end{array}\right)$
$\left(\begin{array}{rl}\mathrm{r} & \mathrm{b}\end{array}\right)=\left(\begin{array}{lll}1 & 1 & 1\end{array}\right)$

## Generic Raster Display Systems



Graphics hardware maintains a 2-D array of pixels: the frame buffer

- values in the frame buffer control intensity of electron beams in CRT
- raster scan process is typically performed at $60-100 \mathrm{~Hz}$

Frame buffers are characterized by

- resolution: dimensions in pixels (eg. $1024 \times 768$ )
- bit depth: \# of bits per pixel (typically 8-24)

Color image and gray-scale image

- $r=g=b \rightarrow$ gray-scale image
- pixel intensity is used instead of RGB channels



## Full-Color Displays

Each pixel contains 3 values, one for each of $R, G$, and $B$

- typically 24 bits/pixel = 8 bits/channel = values of 0-255
- integer values $0-255$ correspond to floating points values $0-1$
- integers are just more convenient in hardware implementation

Pixel values directly control intensity of electron beams

- $\mathrm{R}=0$ implies red beam is off 0

R

- $\mathrm{R}=255$ implies red beam at full intensity

24 bits/pixel generally considered "full-color"

- produces $2^{24} \approx 16$ million different colors
- high-end systems might support 36 bits/pixel or more


## Color Display Via Lookup Tables

Alternative to direct RGB values

- single value per pixel
- typically 8 or 16 bits
- pixel value is an index into a color lookup table or palette

Common when memory is scarce

- can customize set of colors to image being displayed
- 256 colors of your choice

Also supports some handy tricks

- can recolor entire image just by changing palette
- animating palette creates interesting effects (eg. glowing)

Pixel Value


RGB to monitor

## Image Compositing

Often want to combine a sequence of images together

- different parts of final image can come from different sources
- TV stations have been doing this for a Inna time


Question: how to handle the overlapped regions?


## Image Compositing

## Introduce a new alpha channel in addition to RGB channels

- the $\alpha$ value of a pixel indicates its transparency
-if $\alpha=0$, pixel is totally transparent
-if $\alpha=1$, pixel is totally opaque
- alternatively, can think of $\alpha$ as the fraction of the pixel actually covered by the stored color
- convenient to work with premultiplied colors

$$
P=\left[\begin{array}{l}
r_{p} \\
g_{p} \\
b_{p} \\
\alpha_{p}
\end{array}\right] \Rightarrow P^{\prime}=\left[\begin{array}{c}
\alpha_{p} r_{p} \\
\alpha_{p} g_{p} \\
\alpha_{p} b_{p} \\
\alpha_{p}
\end{array}\right] \quad \underbrace{}_{\text {Area } \alpha}
$$

## Image Compositing

Compositing one image over another is most common choice

- can think of each image drawn on a transparent plastic sheet
- the final image is formed by stacking layers together

Given images $\boldsymbol{A} \& \boldsymbol{B}$, we can compute $\boldsymbol{C}=\boldsymbol{A}$ over $\boldsymbol{B}$

$$
C_{r g b}=\alpha_{A} A_{r g b}+\left(1-\alpha_{A}\right) \alpha_{B} B_{r g b}
$$

- if we pre-multiply $\alpha$ values, this simplifies to

$$
C^{\prime}=A^{\prime}+\left(1-\alpha_{A}\right) B^{\prime}
$$



This is only one possible compositing operator

- there are in fact 12 possible ways of combining 2 images


## Example: Image Compositing

Read RGB $\alpha$ values from frame buffer
Given RGB colors $A=(0.8,0.6,1.0)$ and $B=(1,1,1) ; \alpha_{A}=0.5 ; \quad \alpha_{B}=0.2$
Premultiply: $A^{\prime}=\alpha_{A} A=(0.4,0.3,0.5) \quad B^{\prime}=\alpha_{B} B=(0.2,0.2,0.2)$

$$
C^{\prime}=A^{\prime}+\left(1-\alpha_{A}\right) B^{\prime}=\left[\begin{array}{c}
0.5 \\
0.4 \\
0.6 \\
0.6
\end{array}\right], \alpha_{C}=0.6
$$

De-premultiply: $C=C^{\prime} / \alpha_{C}=(0.83,0.67,1.0)$

Write C (RGB $\alpha$ values) back into frame buffer

## Next Time: Basic Geometric Primitives

We'll look at the simplest tools for representing geometry

- lines, planes, triangles, and polygons

We'll also look at some OpenGL basics

- this will help you with your projects


## Reading Assignment

Chapter 1 of Angel

