## On the Midterm Exam

- Monday, $10 / 17$ in class
- Closed book and closed notes
- One-side and one page cheat sheet is allowed
- A calculator is allowed
- Covers the topics until the class on Wednesday, 10/12


## Take-home Quiz

It will be posted in dropbox Wednesday, Oct 12 at 5pm
Submit your solution through dropbox at 2am, Thursday, Oct13.

You can either type or take a picture of your handwritten answer. Please keep your original hard copy for reference.

## Topics

## Perspective Projection

Review for Midterm

## Projections and View Normalization

The default projection is orthogonal (orthographic) projection

Most graphics systems use view normalization

- All other views are converted to the orthographic view by distorting the objects -normalization
- Allows use of the same pipeline for all views

E. Angel and D. Shreiner


## Oblique Projections

The OpenGL projection functions cannot produce general parallel projections - the oblique projection

Oblique Projection $=$ Shear + Orthogonal Projection

$$
\mathbf{P}=\mathbf{M}_{\text {orth }} \mathbf{S T H}(\theta, \phi)
$$

## Effect on Clipping

The projection matrix $\mathbf{P}=$ STH transforms the original clipping volume to the default clipping volume


## Perspective with OpenGL

View volume is determined by the angle of view (field of view)


## Perspective Transformation

## Perspective transformation is

- Not linear
- Not affine
- Not reversible


## Simple Perspective with OpenGL

Consider a simple perspective with

- the COP at the origin,
- the near clipping plane at $z=-1$, and
- a 90 degree field of view determined by the planes $x$
$= \pm z, y= \pm z$
- Perspective projection matrix is

$$
\mathbf{M}=\left[\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 1 / d & 0
\end{array}\right] \text { where } \mathrm{d}=-1
$$



E. Angel and D. Shreiner:

## Perspective Projection and Normalization

The projection can be achieved by view normalization and an orthographic projection
A point $P=(x, y, z, 1)$ is project to a new point $Q$ on the projection plane as

$$
\begin{gathered}
Q=\mathbf{M}_{\text {orth }} \mathbf{N P} \\
\mathbf{N}=\left[\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & \alpha & \beta \\
0 & 0 & -1 & 0
\end{array}\right]
\end{gathered}
$$

## Normalization Transformation

Original clipping volume
Normalized clipping volume

E. Angel and D. Shreiner

## OpenGL Perspective

## How do we handle the asymmetric frustum?

Convert the frustum to a symmetric one by performing a shear followed by a scaling to get the normalized perspective volume.

The final perspective matrix

$$
\mathbf{M}_{\boldsymbol{p}}=\mathbf{N S H}=\left[\begin{array}{cccc}
\frac{2 \text { near }}{\text { right }- \text { left }} & 0 & \frac{\text { left }+ \text { right }}{\text { right }- \text { left }} & 0 \\
0 & \frac{2 \text { near }}{\text { top }- \text { bottom }} & \frac{\text { bottom }+ \text { top }}{\text { top }- \text { bottom }} & 0 \\
0 & 0 & \frac{\text { near }+ \text { far }}{\text { near }- \text { far }} & \frac{\text { 2near } * \text { far }}{\text { near }- \text { far }} \\
0 & 0 & -1 & 0
\end{array}\right]
$$

A point $\mathrm{P}=(\mathrm{x}, \mathrm{y}, \mathrm{z}, 1)$ is project to a new point Q on the projection plane as

$$
Q=\mathbf{M}_{\text {orth }} \mathbf{M}_{\boldsymbol{p}} \mathbf{P}
$$

## An Example

A camera located at eye $=\left[\begin{array}{l}0 \\ 1 \\ 0\end{array}\right]$ is looking at the origin of the object frame at $=\left[\begin{array}{l}0 \\ 0 \\ 0\end{array}\right]$ with the up vector defined as up $=\left[\begin{array}{l}1 \\ 0 \\ 0\end{array}\right]$. The frustum is defined by left $=-1$, right $=2$, bottom $=-1$, top $=2$, near $=2$, and $\mathrm{far}=3$.

For a point $P=\left[\begin{array}{l}1 \\ 2 \\ 3 \\ 1\end{array}\right]$ in the object frame, where its projection $Q$ on the projection plane $z=-1$ ?

## An Example

$$
Q=\mathbf{M} P
$$

What types of transformation we need?

- Model-view
- projection

$$
Q=\mathbf{M}_{p} \mathbf{M}_{v} P
$$

## An Example - Calculate Model View Matrix

How to build the model view matrix?
LookAt(eye, at, up)
Step 1: Calculate the normalized view plane normal

$$
\begin{gathered}
\mathbf{v p n}=\mathbf{a t}-\mathbf{e y e}=\left[\begin{array}{l}
0 \\
0 \\
0
\end{array}\right]-\left[\begin{array}{l}
0 \\
1 \\
0
\end{array}\right]=\left[\begin{array}{c}
0 \\
-1 \\
0
\end{array}\right] \\
\mathbf{n}=\frac{\mathbf{v p n}}{|\mathbf{v p n}|}=\left[\begin{array}{c}
0 \\
-1 \\
0
\end{array}\right]
\end{gathered}
$$

Step 2: Calculate the other two vectors

$$
\begin{gathered}
\mathbf{u}=\frac{\mathbf{u p} \times \mathbf{n}}{|\mathbf{u p} \times \mathbf{n}|}=\left[\begin{array}{c}
0 \\
0 \\
-\overline{1}
\end{array}\right] \\
\mathbf{v}=\frac{\mathbf{n} \times \mathbf{u}}{|\mathbf{n} \times \mathbf{u}|}=\left[\begin{array}{l}
1 \\
0 \\
0
\end{array}\right]
\end{gathered}
$$

## An Example - Calculate Model View Matrix

LookAt(eye, at, up)
Step 3: Construct the model view matrix

$$
\mathbf{M}_{v}=\left[\begin{array}{cccc}
-u_{x} & -u_{y} & -u_{z} & -\mathbf{u} \cdot \mathbf{v p n} \\
v_{x} & v_{y} & v_{z} & \mathbf{v} \cdot \mathbf{v p n} \\
-n_{x} & -n_{y} & -n_{z} & -\mathbf{n} \cdot \mathbf{v p n} \\
0 & 0 & 0 & 1
\end{array}\right]=\left[\begin{array}{cccc}
0 & 0 & 1 & 0 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & -1 \\
0 & 0 & 0 & 1
\end{array}\right]
$$

## An Example - Calculate Projection Matrix

## How to build the projection matrix?

Frustum(left, right, bottom, top, near, far);
Note that this is the case of asymmetric frustum

$$
\begin{aligned}
& \begin{array}{l}
\left.\mathbf{M}_{\boldsymbol{p}}=\mathbf{M}_{\text {orth }} \mathbf{N S H}=\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1
\end{array}\right]\left[\begin{array}{c}
\frac{\text { near }}{\text { right }- \text { left }} \\
0 \\
0 \\
0
\end{array}\right.
\end{array} \\
& \left.\begin{array}{ccc}
0 & \frac{\text { left }+ \text { right }}{\text { right }- \text { left }} & 0 \\
\frac{2 \text { near }}{\text { top }- \text { bottom }} & \frac{\text { bottom }+ \text { top }}{\text { top }- \text { bottom }} & 0 \\
0 & \frac{\text { near }+ \text { far }}{\text { near }- \text { far }} & \frac{2 \text { near } * \text { far }}{\text { near }- \text { far }} \\
0 & -1 & 0
\end{array}\right] \\
& =\left[\begin{array}{cccc}
\frac{2 \text { near }}{\text { right }- \text { left }} & 0 & \frac{\text { left }+ \text { right }}{\text { right }- \text { left }} & 0 \\
0 & \frac{2 \text { near }}{\text { top }- \text { bottom }} & \frac{\text { bottom }+ \text { top }}{\text { top }- \text { bottom }} & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & -1 & 0
\end{array}\right]=\left[\begin{array}{cccc}
\frac{\mathbf{4}}{3} & 0 & \frac{1}{3} & 0 \\
0 & \frac{4}{3} & \frac{1}{3} & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & -1 & 0
\end{array}\right]
\end{aligned}
$$

## An Example

$$
Q=\mathbf{M}_{p} \mathbf{M}_{v} P=\left[\begin{array}{cccc}
\frac{4}{3} & 0 & \frac{1}{3} & 0 \\
0 & \frac{4}{3} & \frac{1}{3} & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & -1 & 0
\end{array}\right]\left[\begin{array}{cccc}
0 & 0 & 1 & 0 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & -1 \\
0 & 0 & 0 & 1
\end{array}\right]\left[\begin{array}{c}
1 \\
2 \\
3 \\
1
\end{array}\right]=\left[\begin{array}{c}
\frac{13}{3} \\
5 \\
\frac{5}{3} \\
0 \\
-1
\end{array}\right]
$$

## Hidden-Surface Removal: Z-buffer algorithm

The circle should be in front of the triangle

## Problem:

The triangle may appear earlier in the pipeline Need to determine which point is the closest

Z-buffer algorithm for hidden-surface removal

- Belongs to image-space algorithm
- Determines the relationship among points on each projector
- Works well in the pipeline


## Hidden-Surface Removal: Z-buffer algorithm

Hidden surface removal works if we first apply the normalization transformation

Recall the perspective projection

$$
\begin{aligned}
& x^{\prime \prime}=-x / z \\
& y^{\prime \prime}=-y / z \\
& z^{\prime \prime}=-(\alpha+\beta / z)
\end{aligned}
$$

For $z_{1}>z_{2}$, the projections $z_{1}{ }^{\prime \prime}>z_{2}{ }^{\prime \prime}$
The order of depth is preserved.

## Hidden-Surface Removal: Z-buffer algorithm

The color of the pixel in the color buffer is determined by the point closest to the viewer - with smaller depth

$$
Q=\mathbf{N S H} P
$$



## Reading Assignments

Chapter 4.9-4.10, Angel \& Shreiner
Chapter 5, Shreiner et al.

