

# Assumption-based Reasoning

Often we want our agents to make assumptions rather than doing deduction from their knowledge. For example:

- In **abduction** an agent makes assumptions to explain observations. For example, it hypothesizes what could be wrong with a system to produce the observed symptoms.
- In **default reasoning** an agent makes assumptions of normality to make predictions. For example, the delivery robot may want to assume Mary is in her office, even if it isn't always true.

# Design and Recognition

Two different tasks use assumption-based reasoning:

- **Design** The aim is to design an artifact or plan. The designer can select whichever design they like that satisfies the design criteria.
- **Recognition** The aim is to find out what is true based on observations. If there are a number of possibilities, the recognizer can't select the one they like best. The underlying reality is fixed; the aim is to find out what it is.

**Compare:** Recognizing a disease with designing a treatment.  
Designing a meeting time with determining when it is.

# The Assumption-based Framework

The assumption-based framework is defined in terms of two sets of formulae:

- $F$  is a set of closed formula called the **facts**. These are formulae that are given as true in the world. We assume  $F$  are Horn clauses.
- $H$  is a set of formulae called the **possible hypotheses** or **assumables**. Ground instance of the possible hypotheses can be assumed if consistent.

# Making Assumptions

- A **scenario** of  $\langle F, H \rangle$  is a set  $D$  of ground instances of elements of  $H$  such that  $F \cup D$  is satisfiable.
- An **explanation** of  $g$  from  $\langle F, H \rangle$  is a scenario that, together with  $F$ , implies  $g$ .  
 $D$  is an explanation of  $g$  if  $F \cup D \models g$  and  $F \cup D \not\models \text{false}$ .  
A **minimal explanation** is an explanation such that no strict subset is also an explanation.
- An **extension** of  $\langle F, H \rangle$  is the set of logical consequences of  $F$  and a maximal scenario of  $\langle F, H \rangle$ .

# Example

$a \leftarrow b \wedge c.$

$b \leftarrow e.$

$b \leftarrow h.$

$c \leftarrow g.$

$c \leftarrow f.$

$d \leftarrow g.$

$\text{false} \leftarrow e \wedge d.$

$f \leftarrow h \wedge m.$

assumable  $e, h, g, m, n.$

- $\{e, m, n\}$  is a scenario.
- $\{e, g, m\}$  is not a scenario.
- $\{h, m\}$  is an explanation for  $a$ .
- $\{e, h, m\}$  is an explanation for  $a$ .
- $\{e, g, h, m\}$  isn't an explanation.
- $\{e, h, m, n\}$  is a maximal scenario.
- $\{h, g, m, n\}$  is a maximal scenario.

# Default Reasoning and Abduction

There are two strategies for using the assumption-based framework:

- **Default reasoning** Where the truth of  $g$  is unknown and is to be determined.  
An explanation for  $g$  corresponds to an **argument** for  $g$ .
- **Abduction** Where  $g$  is given, and we are interested in explaining it.  $g$  could be an observation in a recognition task or a design goal in a design task.